mTask

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Schedule

TOP

iTasks

mTask

Architecture

Thermostat

Concept

Coordinate collaboration between people and machines to reach common goal.

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Components

Declarative paradigm:

- ► Basic tasks: input/output (e.g. web editors)
- ► Composition: sequential, parallel
- ► Communication: task results, shared data

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Implementations

iTasks Generates a multi-user web application from the TOP specification to do the work.

TOP Formally calculus for tasks including operational semantics. mTask TOP language and ecosystem for microcontrollers.

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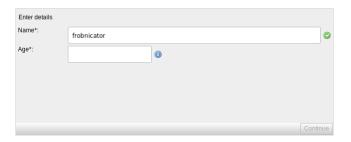
- ▶ DSL in Clean
- ► TOP for the web
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- Support for distributed operation

- ▶ DSL in Clean
- ► TOP for the web
- ► Heavily depends on:
 - ► Polytypic functions (generics)
 - Dynamic typing (dynamics)
- ► Generates a multi-user web application from the specification
- Support for distributed operation
- ► Limited support for peripherals

Basic Tasks

```
return :: a → Task a | iTask a
updateInformation :: d [UpdateOption m m] m → Task m | toPrompt d & iTask m
viewInformation :: d [ViewOption m] m → Task m | toPrompt d & iTask m
:: ViewOption a = \exists v: ViewAs (a \rightarrow v) & iTask v
                |\exists v: ViewUsing (a \rightarrow v) (Editor v) & iTask v
:: EnterOption a = \exists v: EnterAs (v \rightarrow a) & iTask v
                \exists v: EnterUsing (v \rightarrow a) (Editor v) & iTask v
:: UpdateOption a b
  =\exists v: UpdateAs (a \rightarrow v) (a v \rightarrow b) & iTask v
  \exists v: UpdateUsing (a \rightarrow v) (a v \rightarrow b) (Editor v) & iTask v
```







```
:: Person = {name :: String, age :: Int}

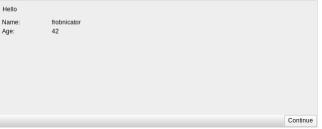
derive class iTask Person

personTask :: Task Person

personTask = enterInformation "Enter details" [] NoValue \( \to \) Unstable \( \to \) Stable

>>= viewInformation "Hello" []

>>= return
```



Combinators

Parallel Combinators

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```
t :: Task Int
t = enterInformation "Left" [] -||- enterInformation "Right []
>>= viewInformation "Result" []
```

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Parallel Combinators

```
t :: Task Int
t = enterInformation "Left" [] -||- enterInformation "Right []
>>= viewInformation "Result" []
Result
```

42

```
t :: Task Int
t = enterInformation "Left" [] -||- enterInformation "Right []
>>= viewInformation "Result" []

t :: Task (Int, Int)
t = enterInformation "Left" [] -&&- enterInformation "Right []
>>= viewInformation "Result" []
```

```
t :: Task (Int, Int)
t = enterInformation "Left" [] -&&- enterInformation "Right []
>>= viewInformation "Result" []
```

Left	
42	
Right	
I	
	Continue

```
t :: Task (Int, Int)
t = enterInformation "Left" [] -&&- enterInformation "Right []
>>= viewInformation "Result" []
```

Left		
42		
Right		
37		

```
(TaskValue a) \rightarrow Maybe b
always :: b
never :: b
                                        (TaskValue a) \rightarrow Maybe b
has Value :: (a \rightarrow b)
                                        (TaskValue a) \rightarrow Maybe b
ifStable :: (a \rightarrow b)
                                        (TaskValue a) → Maybe b
ifUnstable :: (a \rightarrow b)
                                    (TaskValue a) \rightarrow Maybe b
ifValue :: (a \rightarrow Bool) (a \rightarrow b) (TaskValue a) \rightarrow Maybe b
ifCond :: Bool b
                                        (TaskValue a) → Maybe b
withoutValue :: (Maybe b)
                                        (TaskValue a) \rightarrow Maybe b
with Value :: (a \rightarrow Maybe b)
                                        (TaskValue a) \rightarrow Maybe b
with Stable :: (a \rightarrow Maybe b)
                                        (TaskValue a) → Maybe b
withUnstable :: (a \rightarrow Maybe b) (TaskValue a) \rightarrow Maybe b
```

```
Enter a palindrome

legol

Ok Cancel
```

Sequential

```
Enter a palindrome

legovogel
```

```
palindrome :: Task (Maybe String)
palindrome = enterInformation "Enter a palindrome" []
  >>* [ OnAction (Action "Ok") (if Value palindrome (\lambda v \rightarrow return (Just v)))
      , OnAction (Action "Cancel") (always (return Nothing))]
  >>= viewInformation "Result is:" []
where
 palindrome s = s == reverse s
                      Result is:
                     legovogel
```

Derived Sequential Combinators

```
(>>=) infixl 1 :: (Task a) (a \rightarrow Task b) \rightarrow Task b | iTask a & iTask b (>>!) infixl 2 :: (Task a) (a \rightarrow Task b) \rightarrow Task b | iTask a & iTask b (>>-) infixl 1 :: (Task a) (a \rightarrow Task b) \rightarrow Task b | iTask a & iTask b (>-|) infixl 1 (>>-) infixl 1 :: (Task a) (a \rightarrow Task b) \rightarrow Task b | iTask a & iTask b (>>^-) infixl 1 :: (Task a) (Task b) \rightarrow Task b | iTask a & iTask b sequence :: [Task a] \rightarrow Task [a] | iTask a
```

SDSs Defining SDSs

```
sharedStore :: String \ a \ \to \ SimpleSDSLens \ a \ | \ JSONEncode\{|*|\} \ a \ \& \ JSONDecode\{|*|\} \ a \ \& \ TC \ a \ withShared \ :: \ b \ ((SimpleSDSLens \ b) \ \to \ Task \ a) \ \to \ Task \ a \ | \ iTask \ a \ \& \ iTask \ b
```

SDSs

Access Tasks

```
get :: (sds () a w) \rightarrow Task a | iTask a & Readable sds & TC w set :: a (sds () r a) \rightarrow Task a | iTask a & TC r & Writeable sds upd :: (r \rightarrow w) (sds () r w) \rightarrow Task w | iTask r & iTask w & RWShared sds watch :: (sds () r w) \rightarrow Task r | iTask r & TC w & Readable, Registrable sds
```

SDSs

Shared Editors

```
\label{eq:continuous} $\operatorname{updateSharedInformation} :: d [\operatorname{UpdateOption} r w] \ (\operatorname{sds} \ () \ r \ w) \to \operatorname{Task} \ r \ | \ \dots $$ \text{viewSharedInformation} :: d [\operatorname{ViewOption} r] \ (\operatorname{sds} \ () \ r \ w) \to \operatorname{Task} \ r \ | \ \dots $$ \text{sharedUpdate} :: \operatorname{Task} \ \operatorname{Int} $$ \text{sharedInt} \to $$ \text{updateSharedInformation} \ () [] \ \operatorname{sharedInt} $$ \to \operatorname{updateSharedInformation} \ () [] \ \operatorname{sharedInt} \ () \ \operatorname{updateSharedInformation} \ () [] \ \operatorname{sharedInt} \ () \ \operatorname{updateSharedInformation} \ () [] \ \operatorname{sharedInformation} \ () \ \operatorname{updateSharedInformation} \ () \ \operatorname{updateSharedInform
```

Example SDS usage

```
\begin{tabular}{ll} share Task :: Task Int \\ share Task = with Shared 42 $\lambda si \rightarrow $ \\ update Shared Information "Updater" [] si \\ -|| view Shared Information "Viewer" [] si \\ \end{tabular}
```

Updater	
42	
Viewer	
42	
	Continue

Example SDS usage

```
shareTask :: Task Int shareTask = withShared 42 \lambdasi\rightarrow updateSharedInformation "Updater" [] si - | | viewSharedInformation "Viewer" [] si
```

Updater	
37a	
Viewer	
42	
	Continue

Example SDS usage

```
\label{eq:shareTask::Task Int} $$ shareTask = withShared 42 $\lambda si \rightarrow updateSharedInformation "Updater" [] si $$ -|| viewSharedInformation "Viewer" [] si $$ $$ shareTask :: Task Int
```

Updater		
37		
Viewer		
37		
	Conti	nue

mTask

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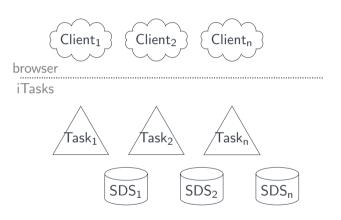
Architecture

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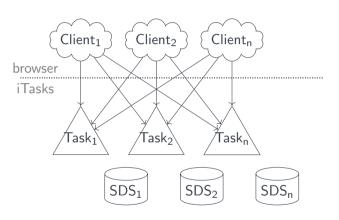
prowser

iTasks

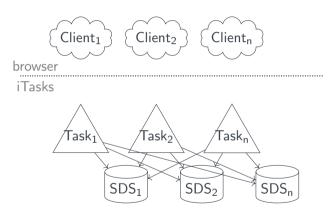
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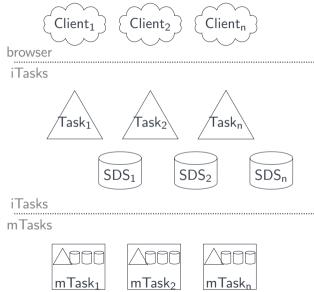
- ► Javascript
- ► Clean
- ► Shared Stores



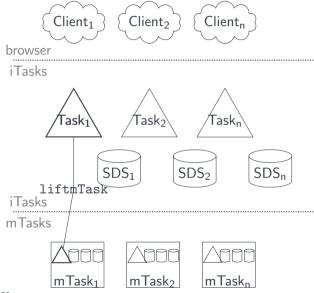
► Type driven UI



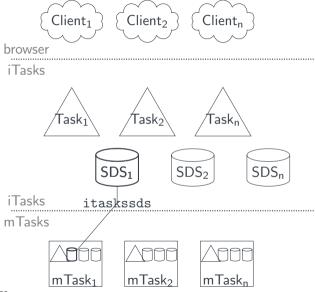
- ► Synchronization
- ► Events



- Devices
- ▶ Tasks
- Shared Stores
- ► RTS/Interpreter



- ► iTasks task as mTask task
- ► Rewrite task
- Synchronize task value



- Synchronize Shared Store
- ► Publish Subscribe

Connecting a device: withDevice

```
:: MTDevice
```

with Device :: (MTDevice \rightarrow Task b) a \rightarrow Task b | channel Sync a & ...

instance channelSync TCPDevice
instance channelSync TTYDevice

Connecting a device: withDevice

```
:: MTDevice
withDevice :: (MTDevice → Task b) a → Task b | channelSync a & ...
instance channelSync TCPDevice
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```

► Literally a single parallel

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:: MTDevice withDevice :: (MTDevice \to Task b) a \to Task b | channelSync a & ... instance channelSync TCPDevice instance channelSync TTYDevice
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- ► Create Channels (withShared)

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- ► Literally a single parallel
- ► Create Channels (withShared)
- ► Setup the connection by running the channel sync

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- ► Run the device task

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- ► Literally a single parallel
- ► Create Channels (withShared)
- ► Setup the connection by running the channel sync
- ► Ask for a specification (embedded in the MTDevice)
- ► Monitor the channels
- ► Run the device task
- ▶ Play some trickery to clean up when the argument task is destroyed

Connecting a device: withDevice

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:: MTDevice withDevice :: (MTDevice \rightarrow Task b) a \rightarrow Task b | channelSync a & ...
```

instance channelSync TCPDevice
instance channelSync TTYDevice

- ► Literally a single parallel
- ► Create Channels (withShared)
- ► Setup the connection by running the channel sync
- ► Ask for a specification (embedded in the MTDevice)
- ► Monitor the channels
- ► Run the device task
- ▶ Play some trickery to clean up when the argument task is destroyed
- ► Close the connection when done

Lifting SDSs: liftSds

```
class liftsds v where liftsds :: ((v (Sds t)) \rightarrow In (Shared t) (Main (MTask v u))) \rightarrow Main (MTask v u) | ...
```

Lifting SDSs: liftSds

```
class liftsds v where
 liftsds :: ((v (Sds t))→In (Shared t) (Main (MTask v u))) → Main (MTask v u) | ...
:: MTLens sds :== Shared sds String255
lens :: ((Shared s1 a) → MTLens s2) | type, iTask a & RWShared s1 & RWShared s2
lens = mapReadWriteError
  (\lambda r \rightarrow 0k \text{ (fromString (toByteCode}\{|*|\} r))
  \lambda w r \rightarrow Just \ll iTasksDecode (toString w)
  ) Nothing
iTasksDecode :: String → MaybeError TaskException a | type a
```

Lifting an mTask to iTasks: liftmTask

 $\texttt{liftmTask} \, :: \, \texttt{MTDevice} \, \, (\texttt{Main} \, \, (\texttt{MTask} \, \, \texttt{BCInterpret} \, \, u)) \, \to \, \texttt{Task} \, \, u \, \mid \, \texttt{iTask}, \, \, \texttt{type} \, \, u$

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► Literally a sequence

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- ► Literally a sequence
- ► Compile the task

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```

- ► Literally a sequence
- ► Compile the task
- ► Retrieve all SDS values

Lifting an mTask to iTasks: liftmTask

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\texttt{liftmTask} :: \texttt{MTDevice} \ (\texttt{Main} \ (\texttt{MTask} \ \texttt{BCInterpret} \ u)) \ \to \ \texttt{Task} \ u \ | \ \texttt{iTask}, \ \mathsf{type} \ u
```

- ► Literally a sequence
- ► Compile the task
- ► Retrieve all SDS values
- ► Ask the device to prepare (slow comm, small buffers)

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- ► Literally a sequence
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- ► Retrieve all SDS values
- ► Ask the device to prepare (slow comm, small buffers)
- ► Send the task

Lifting an mTask to iTasks: liftmTask

 $\texttt{liftmTask} :: \texttt{MTDevice} \ (\texttt{Main} \ (\texttt{MTask} \ \texttt{BCInterpret} \ \texttt{u})) \ \to \ \texttt{Task} \ \texttt{u} \ | \ \texttt{iTask}, \ \texttt{type} \ \texttt{u}$

- ► Literally a sequence
- ► Compile the task
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- ► Ask the device to prepare (slow comm, small buffers)
- ► Send the task
- ► Wait for it to return

Lifting an mTask to iTasks: liftmTask

 $\texttt{liftmTask} :: \texttt{MTDevice} \ (\texttt{Main} \ (\texttt{MTask} \ \texttt{BCInterpret} \ u)) \ \to \ \texttt{Task} \ u \ | \ \texttt{iTask}, \ \mathsf{type} \ u$

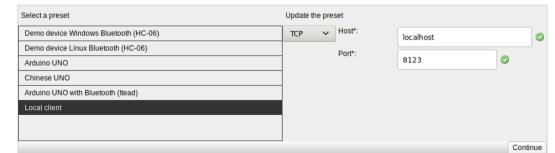
- ► Literally a sequence
- ► Compile the task
- Retrieve all SDS values
- ► Ask the device to prepare (slow comm, small buffers)
- ► Send the task
- ► Wait for it to return
- ► Watch all linked SDSs both ways

Lifting an mTask to iTasks: liftmTask

```
\texttt{liftmTask} :: \texttt{MTDevice} \ (\texttt{Main} \ (\texttt{MTask} \ \texttt{BCInterpret} \ u)) \ \to \ \texttt{Task} \ u \ | \ \texttt{iTask}, \ \mathsf{type} \ u
```

- ► Literally a sequence
- ► Compile the task
- Retrieve all SDS values
- ► Ask the device to prepare (slow comm, small buffers)
- ► Send the task
- ► Wait for it to return
- ► Watch all linked SDSs both ways
- ► Relay the task value to the task itself

Thermostat



```
main :: Task ((), ())
main = enterDevice

>>= withDevice \( \lambda \delta \rightarrow
\)
withShared (160,220) \( \lambda \targets \rightarrow
\)
withShared 420 \( \lambda \targets \rightarrow
\)
updateSharedInformation "Targets" [targetUpdater] targets
||- viewSharedInformation "Current" [ViewAs targetView] temp
||- liftmTask dev (mTask targets temp)
```

- ► Connect to the device
- ► Start the synchronization task
- ► Ask for a specification
- ► Wait for the specification to return

```
main :: Task ((), ())
main = enterDevice

>>= withDevice λdev→

withShared (160,220) λtargets→

withShared 420 λtemp→

updateSharedInformation "Targets" [targetUpdater] targets

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```

```
main :: Task ((), ())
main = enterDevice
  >>= withDevice \lambda \text{dev} \rightarrow
      with Shared (160,220) \lambda targets \rightarrow
      with Shared 420 \lambda temp\rightarrow
           updateSharedInformation "Targets" [targetUpdater] targets
        ||- viewSharedInformation "Current" [ViewAs targetView] temp
Targets
Low*:
                16
High*:
                22
Current
43.9
```

```
main :: Task ((), ())
main = enterDevice
>>= withDevice \( \lambda \text{ev} \rightarrow
\) withShared (160,220) \( \lambda \text{targets} \rightarrow
\) withShared 420 \( \lambda \text{temp} \rightarrow
\) updateSharedInformation "Targets" [targetUpdater] targets
\[ |- viewSharedInformation "Current" [ViewAs targetView] temp
\[ |- liftmTask dev (mTask targets temp) \]
```

- ► Compile the task
- ► Send the task
- ► Wait for acknowledgement
- ► Synchronize lifted SDSs

```
mTask targetShare tempShare =

DHT DHTPIN DHT22 \( \lambda \text{th} \to \)

liftsds \( \lambda \text{target} = \text{targetShare } \text{In} \)

liftsds \( \lambda \text{target} = \text{tempShare } \text{In} \)

{main

= ever (temperature dht >> \times setSds temp >> | . delay (lit 2000))

.&&. ever (getSds temp .&&. getSds target >> \times tupopen (temp, target) → \( \lambda \text{v} \rightarrow \text{writeD FANPIN } \)

writeD FANPIN (temp < . second target)

.&&. writeD HEATPIN (temp > . first target)

)}
```

```
mTask targetShare tempShare =

DHT DHTPIN DHT22 \( \lambda \text{th} \to \)

liftsds \( \lambda \text{target} = \text{targetShare In} \)

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{main

= ever (temperature dht >>>. setSds temp >>|. delay (lit 2000))

.&&. ever (getSds temp .&&. getSds target >>>. tupopen (temp, target) → \( \lambda \text{v} \rightarrow \)

writeD FANPIN (temp <. second target)

.&&. writeD HEATPIN (temp >. first target)

}}
```

```
mTask targetShare tempShare =

DHT DHTPIN DHT22 \( \lambda \text{th} \to \)

liftsds \( \lambda \text{target} = \text{targetShare } \text{In} \)

liftsds \( \lambda \text{temp} = \text{tempShare } \text{In} \)

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liftsds \( \lambda \text{temp} = \text{tempShare } \)

{main

= ever (temperature dht >> \times \text{setSds temp} >> | \text{. delay (lit 2000)})

.&&. ever (getSds temp .&&. getSds target >> \times \text{tupopen (temp, target)} \( \text{→} \text{\text{v}} \)

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fmain

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.&&. ever (getSds temp .&&. getSds target >>>. tupopen (temp, target) → \( \lambda \text{v} \rightarrow \text{writeD FANPIN (temp <. second target)} \)

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```

► Questions?

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► Exceptions/interrupts

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- ► Collaborate?